





COSCH^{KR}: how does the inference work

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Technologies



Measurement Principles

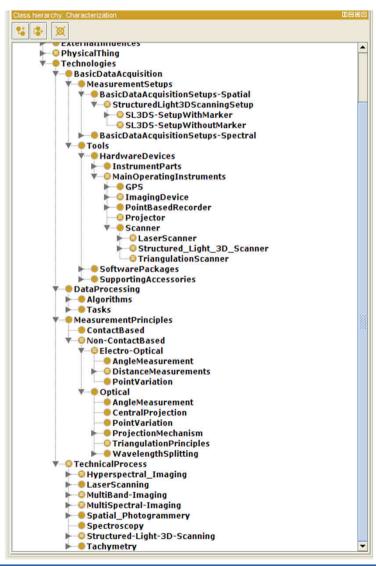
those actually are responsible for data generation

Tools

- Instruments
 - based on measurement principles and responsible for data generations
- Setups
 - setups with instruments and necessary accessories for optimal data generations

Data Processing

- post processing algorithms and tasks for end data product
- Technical Process
 - packages all technical components







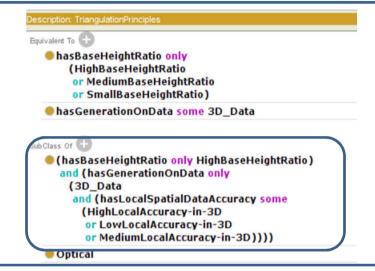








- Measurement Principles
 - Triangulations



Angle Measurement / Distance
 Measurement

```
Description: AngleMeasurement

Equivalent To +

SubClass Of +

Electro-Optical

hasInCombination only (DistanceMeasurements and (hasGenerationOnData only ((3D_Data and (hasLocalSpatialDataAccuracy some (HighLocalAccuracy-in-3D or LowLocalAccuracy-in-3D or MediumLocalAccuracy-in-3D))))))

Optical
```

Central Projection

```
hasGenerationOnData only
(2D_Data
and (hasLocalSpatialDataAccuracy
some
(MediumLocalAccuracy-in-2D
or LowLocalAccuracy-in-2D)))
```







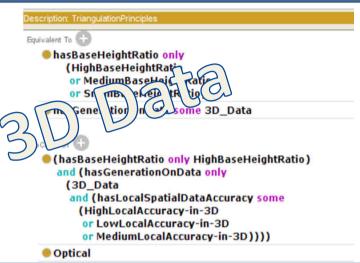




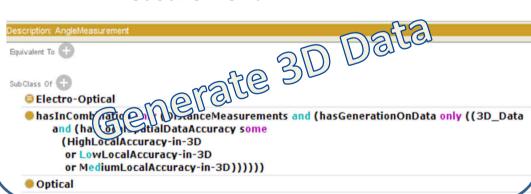
Technologies: Principles

- Measurement Principles
 - Triangulations





Angle Measurement / Distance Measurement



Central Projection

```
hasGenerationOnData only
(2D_Data
and (hasLocalSpetio DataAccuracy
some
(Mediu LocalAccuracy-in-2D
or LowLocalAccuracy-in-2D)))
```











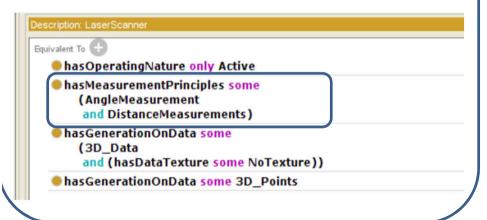
- Main Hardware
 - Structured Light Scanner(Triangulation)

Description: Structured Light_3D_Scanner

Equivalent To hasGenerationOnData some 3D_Mesh
hasOperatingNature only Active
(hasEssentials min 1 Camera)
and (hasEssentials exactly 1 Projector)
hasMeasurementPrinciples only TriangulationPrinciples

Laser Scanner

(Distance/Angle Measurement)



Camera(Central Projection)

Sub Class Of (Anonymous Ancestor)

hasGenerationOnData only BasicData
 hasOperatingNature only OperatingNature
 hasMeasurementPrinciples some MeasurementPrinciples
 hasMeasurementPrinciples only CentralProjection





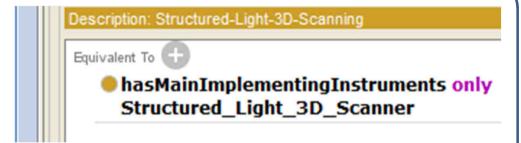






Technologies: Technical Process

 Structured Light Scanning (Structured Light Scanner)



Structure from

 Laser Scanning (Laser Scanner)

Description: LaserScanning

Equivalent To
hasMainImplementingInstruments only
LaserScanner

Motion

(Camera)

Description: Structure_from_Motion

Equivalent To
(hasDataProcessingTask some 3DGeneration)
and (hasGenerationOnData only 3D_Data)

hasMainImplementingInstruments only Camera









Technologies: Technical Process

• Structured Light Scanning (Structured Light Scanner)

Description: Structured-Light anning

Equivalent to the lain Implementing Instruments only

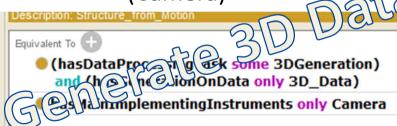
Structured_Light_3D_Scanner

Laser Scanning

(Laser Scanner)



Structure from Motion (Camera)













CH Application (Deformation Analysis)

















Structured Light Scanning

Instrument: Structured Light Scanner

Principle: Triangulation

Laser Scanning

Instrument: Laser Scanner

Principle: Distance/Angle Msmnt

Structure from Motion

Instrument: Camera

Principle: Central Projection

```
Sub Class Of
  (hasBaseHeightRatio only HighBaseHeightRatio)
     and (hasGenerationOnData only
      (3D Data
       and (hasLocalSpatialDataAccuracy some
         (HighLocalAccuracy-in-3D
         or LowLocalAccuracy-in-3D
         or MediumLocalAccuracy-in-3D))))
```

```
hasInCombination only
    (DistanceMeasurements
    and (hasGenerationOnData only
      (3D Data
      and (hasLocalSpatialDataAccuracy some
        (HighLocalAccuracy-in-3D
         or LowLocalAccuracy-in-3D
         or MediumLocalAccuracy-in-3D)))))
```

```
Sub Class Of
  hasGenerationOnData only
      (2D_Data
       and (hasLocalSpatialDataAccuracy
    some
    (HighLocalAccuracy-in-2D or
    MediumLocalAccuracy-in-2D
     or LowLocalAccuracy-in-2D)))
```











Technologies: Technical Process

Structured Light Scanning

Instrument: Structur Light Scaller Principle: Triangulat

Sub Class Of (hasBaseHeightRatio only HighBaseHeightRatio) and (hasGenerationOnData only or MediumLocalAccuracy-in-3D))))

Laser Scanning

Instrument: Laser Screen

Principle: Distance/

hasInCombination only (DistanceMeasurements and (hasGenerationOnData only (3D Data and (Instructional Spatial Data Accuracy some or MediumLocalAccuracy-in-3D)))))

Structure from Motion

Instrument: Camera Projection — Principle: Central Projection

and (hasLocalSpatialDataAccuracy

(2D_Data

hasGenerationOnData only

Sub Class Of











CH Application (Deformation Analysis)















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CH Application (Deformation Analysis)



Data(High Accuracy 3D Data)





Objects



Reflectivity:

Quantity:

Texture:

Condition:



Technology









- Main Hardware
 - Structured Light Scanner

```
Description: Structured_Light_3D_Scanner

(hasEssentials min 1 Camera)
and (hasEssentials exactly 1 Projector)
hasMeasurementPrinciples only TriangulationPrinciples

SubClass Of (hasCost some High_Cost)
and (hasOperatingProject some
(Projects
and (hasOperatingProject some High_Budget)))

isSuitabilitiesFor some
(PhysicalThing
and ((hasObjectSize some 2DSize_Small)
or (hasObjectVolume some 3DVolume_Small)))
```

Laser Scanner

```
( hasCost some High_Cost)
and (hasOperatingProject some
    (Projects
    and (hasProjectBudgetRange some High_Budget)))

isSuitabilitiesFor some
    (PhysicalThing
    and (hasObjectTexture some
        (Non-Textured
        or Textured)))

isSuitabilitiesFor some
    (PhysicalThing
    and (hasObjectVolume some
        (3DVolume_Big
        or 3DVolume Medium)))
```

Camera

```
Subclass of ImagingDevice

isSuitabilitiesFor some
(PhysicalThing
and (hasObjectVolume some
(3DVolume_Big
or 3DVolume_Medium
or 3DVolume_Small)))
```











- **Main Hardware**
 - stsultability: Small

```
(hasEssentials min 1 Camera)
  and (hasEssentials exactly 1 Projector)
hasMeasurementPrinciples only TriangulationPrinciples
    and (hasProjectBudgetRange some High_Budget)))
 isSuitabilitiesFor some
    (PhysicalThing
    and ((hasObjectSize some 2DSize_Small)
    or (hasObjectVolume some 3DVolume Small)))
```

Laser Scanner Sub Class Of (hasCost some High Cost) and (hasOperatingProject some (Projects and (hasProjectBudgetRange some High_Budget))) isSuitabilitiesFor some or Textured))) is@uitabilitiesFor some (PhysicalThing and (hasObjectVolume some (3DVolume Big or 3DVolume Medium)))

Camera Sub Class Of ImagingDevice and (hasObjectVolume some or 3DVolume Small)))





Programme Horizon 2020









- Main Hardware
 - Structured Light Scanner

```
Other Structured Light 3D_Scanner

(has Essentials min 1 Camera)
and (has Essentials exactly 1 Projector)
has Measurement Principles only Triangulation Principles

(has Cost some High_Cost)
and (has Operating Project some
(Projects
and (has Project Budget Range some High_Budget)))

(is Suitabilities For some
(Physical Thing
and ((has Object Size some 2D Size_Small)
or (has Object Volume some 3D Volume_Small)))
```

Laser nner Sub Class Of (hasCost High_Cost ingProje and (has (Projects and (hasP ange some High_Budget))) isSuitabilitiesF (PhysicalThine and (hasObj some (Non-Tex or Text is Suitabili (Phys bjectVolume ume Big Volume Medium))

- Camera

SubClass Of ImagingDevice

ImagingDevice

isSuitabilitiesFor some
(PhysicalThing
and (hasObjectVolume some
(3DVolume_Big
or 3DVolume_Medium
or 3DVolume_Small)))









Technologies: Technical Process

 Structured Light Scanning (Structured Light Scanner) Description: Structured-Light-3D-Scanning

Equivalent To hasMainImplementingInstruments only
Structured_Light_3D_Scanner

• Laser Scan
(Laser Scanning

Description: LaserScanning

Equivalent To
hasMainImplement A uments only LaserScanner

- Structure from
Motion
(Camera)

Description: Structure_from_Motion

Equivalent To (hasDataProcessingTask some 3DGeneration)
and (hasGenerationOnData only 3D_Data)
hasMainImplementingInstruments only Camera











CULTURAL HERITAGE



Objects

Size: Small

* Reflectivity:

Quantity:

Texture:

Condition:







CH Application (Deformation Analysis)

Data(High Quality 3D Data)



Technology







CULTURAL HERITAGE



CH Application (Deformation Analysis)



Objects

Size: Small

* Reflectivity:

Quantity:

Texture: Non-Textured

Condition:



Data(High Accuracy 3D Data)



Technology







- Main Hardware
 - Structured Light Scanner

```
Description: Structured_Light_3D_Scanner

Equivalent To hasOperatingNature only Active (hasEssentials min 1 Camera)
and (hasEssentials exactly 1 Projector)

hasMeasurementPrinciples only TriangulationPrinciples hasGenerationOnData some 3D_Data
```

Laser Scanner

Description: LaserScanner

hasOperatingNature only Active
hasMeasurementPrinciples some
(AngleMeasurement
and DistanceMeasurements)

hasGenerationOnData some
(3D_Data
and (hasDataTexture some NoTexture))

hasGenerationOnData some 3D_Points

- Camera

Description: Camera

hasEssentials min 1 Lens
hasEssentials some CameraParts
hasGenerationOnData some
(AdditionalData
and (hasImageScale some
(ImageScale-High
or ImageScale-Low
or ImageScale-Medium)))
hasOperatingNature only Passive









Instruments: Operating Nature



Active

Passive

```
Description: Active
Equivalent To
   isCharacteristicsOf some
       (MainOperatingInstruments
        and (isSuitabilitiesFor some
         (PhysicalThing
          and (hasObjectAppearance some
            (Non-Textured
             or Textured)))))
```

```
Description: Passive
Equivalent To
   isCharacteristicsOf some
       (MainOperatingInstruments
        and (isSuitabilitiesFor some
          (PhysicalThing
          and (hasObjectAppearance some
     (not Non-Textured)))))
```







Instruments: Operating Nature



Description: Active Active Equivalent To isCharacteristicsOf some (MainOperatingInstruments and (isSuitabilitiesFor some (PhysicalThing and (hasObjectAppearance some (Non-Textured or Textured))))) Description sCharacteristicsOf some Passive (MainOperatingInstruments and (isSuitabilitiesFor some (PhysicalThing and (hasObjectAppearance some Non-Textured)))))









- Main Hardware
 - Structured Light Scanner

```
Description: Structured_Light_3D_Scanner

Equivalent To 
hasOperatingNature only Active
(hasEssentials min 1 Camera)
and (hasEssentials exactly 1 Projector)
hasMeasurementPrinciples only TriangulationPrinciples
hasGenerationOnData some 3D_Data
```

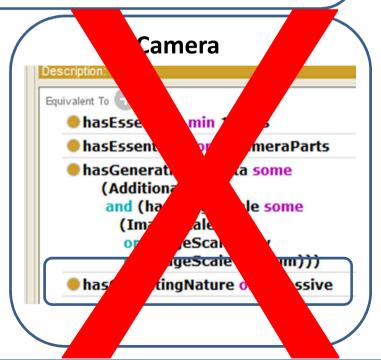
- Laser Scanner

Description: LaserScanner

Lequivalent To the hasOperatingNature only Active hasMeasurementPrinciples some (AngleMeasurement and DistanceMeasurements)

hasGenerationOnData some (3D_Data and (hasDataTexture some NoTexture))

hasGenerationOnData some 3D_Points













Technologies: Technical Process

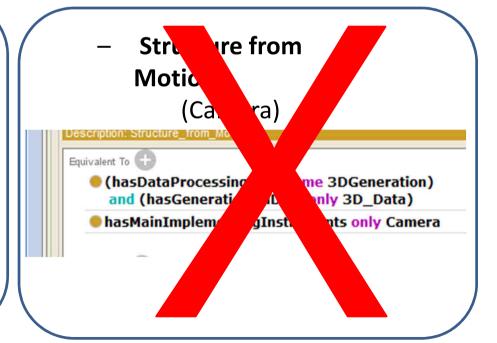
 Structured Light Scanning (Structured Light Scanner)



Laser Scanning
 (Laser Scanner)

Description: LaserScanning

Equivalent To
hasMainImplementingInstruments only
LaserScanner













Technologies: Technical Process

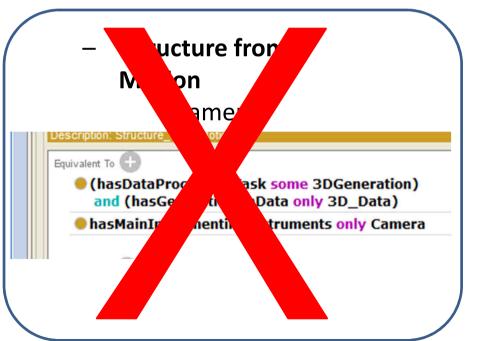
 Structured Light Scanning (Structured Light Scanner) Description: Structured-Light-3D-Scanning

Equivalent To
hasMainImplementingInstruments only
Structured_Light_3D_Scanner

• Laser Scanning
(Laser Scanning

Description: LaserScanning

Equivalent To hasMainImplement A uments only LaserScanner













CULTURAL HERITAGE



CH Application (Deformation Analysis)

Objects

Size: Small

* Reflectivity:

Quantity:

Texture: Non-Textured

Condition:





Data(High Quality 3D Data)



Technology







CULTURAL HERITAGE

CH Application (Deformation Analysis)



Data(High Quality 3D Data)





Size: Small

Reflectivity: High

Quantity:

Texture: Non-Textured

Condition:



Technology









Technologies: Principles



- **Triangulations**
 - Structured Light Scanner -**Structured Light Scanning**
- **Angle/Distance Measurements**
 - Laser Scanner Laser Scanning
- **Central Projection**
 - Camera Structure from Motion

```
(hasGenerationOnData some
    (BasicData
    and (hasLocalSpatialDataAccuracy some
      (HighLocalAccuracy-in-2D
      or HighLocalAccuracy-in-3D))))
  and (hasOperatingOnObject some
    (PhysicalThing
    and (hasObjectReflectance some Low_Reflectivity)))
 (hasGenerationOnData some
    (BasicData
    and (hasLocalSpatialDataAccuracy some (LowLocalAccuracy-in-3D)
  or (LowLocalAccuracy-in-2D))))
  and (hasOperatingOnObject some
   (PhysicalThing
    and (hasObjectReflectance some High_Reflectivity)))
(hasGenerationOnData some
   (BasicData
    and (hasLocalSpatialDataAccuracy some (MediumLocalAccuracy-in-3D)
 or (MediumLocalAccuracy-in-2D))))
  and (hasOperatingOnObject some
   (PhysicalThing
    and (hasObjectReflectance some Moderate_Reflectivity)))
MeasurementPrinciples
```









Technologies: Principles



- lations
 - red Ligh anner – Struc Scanning
- Angle/Dist Measurements
 - Laser Scanning ann Lase
- Cent rojection
 - mera Structur m Motion

```
(hasGenerationOnData some
    (BasicData
    and (hasLocalSpatialDataAccuracy some
      (HighLocalAccuracy-in-2D
      or HighLocalAccuracy-in-3D))))
  and (hasOperatingOnObject some
    (PhysicalThing
    and (hasObjectReflectance some Low_Reflectivity)))
  or (Low ( )Accuracy-in-2D)
  and (hasOperatingOnObject some
   (PhysicalThing
    and (has bbj
   (BasicData
    and (hasLocalSpatialDataAccuracy some (MediumLocalAccuracy-in-3D)
 or (MediumLocalAccuracy-in-2D))))
  and (hasOperatingOnObject some
   (PhysicalThing
    and (hasObjectReflectance some Moderate_Reflectivity)))
MeasurementPrinciples
```









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CH Application (Deformation Analysis)



She: Small Reflectivity: High

Quantity:

Texture: Non-Textured

Condition: Fragile

Technology









Technologies: Principles



- **Triangulations**
 - Structured Light Scanner -**Structured Light Scanning**
- **Angle/Distance Measurements**
 - Laser Scanner Laser Scanning
- **Central Projection**
 - Camera Structure from Motion

```
(hasGenerationOnData some
    (BasicData
    and (hasLocalSpatialDataAccuracy some
      (HighLocalAccuracy-in-2D
      or HighLocalAccuracy-in-3D))))
  and (hasOperatingOnObject some
    (PhysicalThing
    and (hasObjectReflectance some Low_Reflectivity)))
(hasGenerationOnData some
    (BasicData
    and (hasLocalSpatialDataAccuracy some (LowLocalAccuracy-in-3D)
  or (LowLocalAccuracy-in-2D))))
  and (hasOperatingOnObject some
   (PhysicalThing
    and (hasObjectReflectance some High_Reflectivity)))
(hasGenerationOnData some
    (BasicData
    and (hasLocalSpatialDataAccuracy some (MediumLocalAccuracy-in-3D)
 or (MediumLocalAccuracy-in-2D))))
  and (hasOperatingOnObject some
   (PhysicalThing
    and (hasObjectReflectance some Moderate_Reflectivity)))
MeasurementPrinciples
```











CULTURAL HERITAGE

CH Application (Deformation Analysis)



Data(High Quality 3D Data)





Size: Small

Reflectivity: Low

Quantity:

Texture: Non-Textured

Condition:



Technology











COLOR & SPACE IN

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CH Application (Deformation Analysis)



Data(High Quality 3D Data)





Size: Small

* Reflectivity: Low

Quantity: Large

Texture: Non-Textured

Condition:



Technology





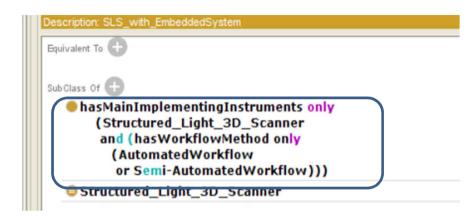








- **Structured Light Scanners**
 - **Automated / Semi-Automated** Workflow



- **Automated / Semi-Automated Workflow**
 - Suitable for large numbers of object

```
Equivalent To
Sub Class Of
  isTechnologiesCharacteristicsOf some
      (MainOperatingInstruments
       and (hasRequirementOnOperatingCompetence some Competence_Low))
  isTechnologiesCharacteristicsOf some
      (MainOperatingInstruments
       and (hasRequirementOnTechnicalCompetence some Competence_High))
  isTechnologiesCharacteristicsOf some
      (MainOperatingInstruments
       and (isSuitabilitiesFor some
        (PhysicalThing
         and (hasObjectQuantity some LargeNumber)))
  Workflow_Method
```





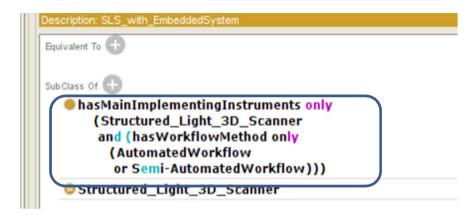




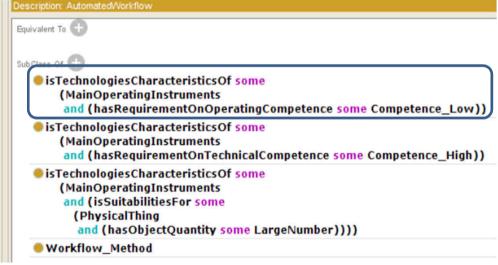




- **Structured Light Scanners**
 - **Automated / Semi-Automated** Workflow



- **Automated / Semi-Automated Workflow**
 - Suitable for operating staff competency: Low









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CH Application (Deformation Analysis)

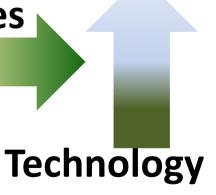


Data(High Accuracy 3D Data)

External Influences

Project

Staff Competence: Low







Size: Small

Reflectivity: Low

Quantity: Large

Texture: Non-Textured

Condition: Fragile



(Structured Light Scanning, Laser Scanning, SfM)





CULTURAL HERITAGE

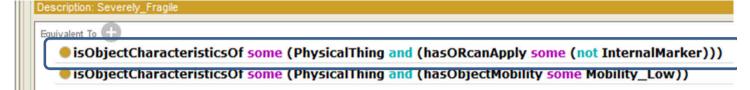




Technologies: Technical Process



Fragile



No internal markers

- **Structured Light Scanning**
 - **Setup with Markers**
 - **Generates highly** accurate data

```
Description: Structured-Light-3D-Scanning
Equivalent To
  hasMainImplementingInstruments only Structured_Light_3D_Scanner
Sub Class Of
    (hasMeasurementSetups some SL3DS-SetupWithMarker)
     and (hasMainImplementingInstruments only
      (Structured Light 3D Scanner
       and (hasGenerationOnData some
         (BasicData
         and (hasAlignedSpatialDataAccuracy only
           (AlianedAcBaSz High-in-3D
           or AlignedAcMdSz High-in-3D
           or AlignedAcSzSm High-in-3D))))))
  (hasMeasurementSetups some SL3DS-SetupWithMarkerandTT)
     and (hasProcessingTime some ShortTime)
  TechnicalProcess
```













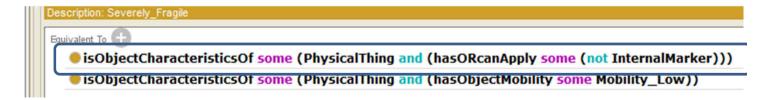
Setup with Markers

 Needs at least 5 internal markers



Object – Fragile

No internal Marker Possible













CULTURAL HERITAGE

CH Application (Deformation Analysis)

Data(Highacc

External Influences

Project ·

Staff Con peterce: Low

blects Reflectivity: Low Quantity: Large

Texture: Non-Textured

Condition: Fragile









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CH Application (Deformation Analysis)



Data(High Quality 3D Data)

External Influences

Project

Staff Competence: Low







Size: Small

Reflectivity: Low

Quantity: Large

Texture: Non-Textured

Condition: Fragile

but internal markers

possible







